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DATA REPORT FOR TESTS OF A 0.055-SCALE APOLLO DYNAMIC STABILITY MODEL (FD-2) TO DETERMINE FLOW SEPARATOR EFFECTS - LANGLEY 8-FOOT TRANSONIC PRESSURE TUNNEL (PROJECT 258) (U)



**April** 1963

CLASSIFICATION CHANGE

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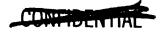




### FOREWORD

The tests to determine flow separator effects were conducted under NASA Apollo contract NAS9-150 in the Langley 8-foot Transonic Pressure Tunnel.

This report was prepared by C. E. Mitchell and C. L. Berthold of the Wind Tunnel Projects Group, Los Angeles Division of North American Aviation, Inc.





# COMPRENTIAL

## CONTENTS

										F	Page
l	INTRODUCTION		•		•						1
11	DISCUSSION				•	•	•	•	•	•	2
Ш	MODEL DESCRIPTION										3
	Model Nomenclature .	•	•	•					•		3
	Full-Scale Dimensions	•	•	•	•	•	•	•	•		4
١٧	TEST PROCEDURE			•							15
	Test Nomenclature .										
	Model Installation .										16
	Instrumentation		•		•						16
	Data Reduction and Const	ants	•								16
	Data Accuracy		•		•	•		•	٠	•	18
٧	REFERENCES			•					•		19
	APPENDIXES										
	A. PLOTTED DATA.			•		•					A - 1
	B. TABULATED DATA										B-1



## **ILLUSTRATIONS**

Figure		Page
1	Launch Escape Configuration Model Assembly	
	(Drawing No. 7121-01072)	5
2	Reentry Configuration Model Assembly	
	(Drawing No. 7121-01059)	6
3	LEV Configuration $E_{52}T_{21}C_{19}$	7
4	Escape Rocket Configurations	8
5	Tower Structure	9
6	Command Module Reentry Configuration Oscillation	
	Center Location	10
7	Command Module for LEV Configuration	11
8	LEV With Flow Separator Disc	12
9	LEV Without Flow Separator Disc	13
10	Command Module Reentry Configuration	14



## I. INTRODUCTION

Dynamic stability tests were conducted on the 0.055-scale Apollo FD-2 model in the Langley 8-foot Transonic Pressure Tunnel (TPT) from 23 October 1962 to 25 October 1962. This investigation was made to determine dynamic stability derivatives for the command module reentry configuration and for a later launch escape configuration (116-inch tower and 280-inch rocket) than used during previous tests.

The launch escape configurations, which were tested at Mach numbers 0.03, 0.70, 0.90, 1.00, and 1.20, included flow separator disc on and off with the oscillation center on the design center of gravity of the full-scale vehicle. Since the command module configuration had not changed, it was tested only at Mach 0.70, 1.00, and 1.20 with an oscillation center not previously used in this Mach number range. Data at this oscillation center, combined with data at three other o'scillation centers from a previous 8-foot TPT test (Reference 1), will allow an investigation of a method for transferring dynamic stability derivatives to centers of gravity other than that at which the test was conducted. All of these oscillation centers were displaced from the design center of gravity because of space limitations (Figure 1).

Reynolds numbers, based on maximum model diameter, were in the order of  $1.75 \times 10^6$  to  $3.76 \times 10^6$ . All dynamic stability derivatives were measured during forced oscillation of the model in pitch only with an amplitude of approximately  $\pm 2$  degrees about the oscillation center. The launch escape configurations were run at nominal angles of attack from -12 to  $\pm 6$  degrees, and the command module was run from  $\pm 136$  to  $\pm 164$  degrees.

This report presents basic wind tunnel data only so that test results can be made available as early as possible. Analysis of results will be reported in a separate publication.





## II. DISCUSSION

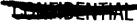
This investigation was conducted primarily to evaluate dynamic stability characteristics of the current launch escape configuration in the subsonic and transonic speed ranges. In previous tests at these Mach numbers, physical limitations imposed by the size of the model and the existing dynamic balance made it impossible to locate the oscillation center ideally on the design center of gravity of the full-scale vehicle. On the current LEV model, the command module apex was modified within the confines of the tower legs to position the balance oscillation center on the design center of gravity. Investigations were made with flow separator disc on and off (configurations  $E_{52}$   $E_{10}$   $E_{10}$  and  $E_{51}$   $E_{10}$   $E_{10}$ .

The command module model was tested at three Mach numbers with a 0.50-inch spacer between the attach point of the model and the balance.

Several techniques are available for measuring dynamic stability derivatives of models in wind tunnels. This test was performed using the "inexorable" method in which the model is mechanically forced to oscillate in a single degree of freedom at a known angular frequency and amplitude (±2 degrees) while measurements are made of the moment required to sustain the motion. A more complete description of the apparatus and methods used can be found in References 1 and 5.

The plotted and tabular data are presented in Appendixes A and B in NASA standard coefficient form referred to the body system of axes originating at the oscillation center. Dynamic stability parameters are employed to indicate aerodynamic damping in pitch ( $C_{m_q} + C_{m_q^*}$ ), and oscillatory longitudinal stability ( $C_{m_q} - k^2 C_{m_q^*}$ ) for tests with oscillations in pitch for the reentry and launch escape configurations. The plotted data present these parameters as a function of angle of attack.

Because of adverse model location in the tunnel, no Schlieren photographs were taken.







### III. MODEL DESCRIPTION

To reduce moment-of-inertia effects, the test models were constructed from lightweight materials whenever consistent with the structural integrity as established in Reference 6. The command modules were constructed of aluminum alloy (7075-T6); the escape tower was constructed of Armco steel (17-4PH SST); and the escape rocket was constructed of magnesium (QQ-M-31). All configurations were aerodynamically smooth. Photographs of the models are shown in Figures 8, 9, and 10.

The apex of the command module for the LEV configurations was modified within the confines of the tower legs to allow the oscillation center of the balance to be positioned on the design center of gravity of the full-scale vehicle (Figure 7). The command module reentry configuration had not changed from previous tests, but a 0.50-inch spacer between the model and balance attach point gave an oscillation center not tested in this Mach number range.

### MODEL NOMENCLATURE

Symbol	Description	Drawing Detail No.	Sketch
E <sub>51</sub>	Escape motor. Length = 279.65 in.; 360 55' flared skirt	7121-01072- 4-11	Figure 4
E <sub>52</sub>	Escape motor. Length = 279.65 in.; 36 <sup>0</sup> 55' flared skirt with 65 in. dia. flow separator disc and fairing from disc to skirt	7121-01072- 4-6-11	Figure 4
T <sub>21</sub>	Tower structure. Length = 116.1 in.	7121-01072-9	Figure 5
C	Command module.  Max. dia. = 154.0 in.	7121-01059	Figure 6
C <sub>19</sub>	Command Module. Max. dia. = 154.0 in.; apex altered to correctly position balance.	7121-01072- 3-5-7	Figure 7



### FULL-SCALE DIMENSIONS

# Escape Rocket, E<sub>51</sub>

Total length	279.65 in.
Diameter	26.00 in.
Nose radius	2.00 in.
Nose included angle	30.00 deg
Skirt base diameter	54.60 in.
Skirt flare angle	36.92 deg
Diameter of ring forward of skirt	28.87 in.

# Escape Rocket, E<sub>52</sub>

Same as E51 with flow separator disc located 19.16 in. from base of rocket motor and a fairing extending from aft end of disc to flared skirt.

Flow separator disc diameter	65.00 in.
Flow separator disc thickness	2.00 in.
Fairing diameter	51.08 in.

## Tower, T21

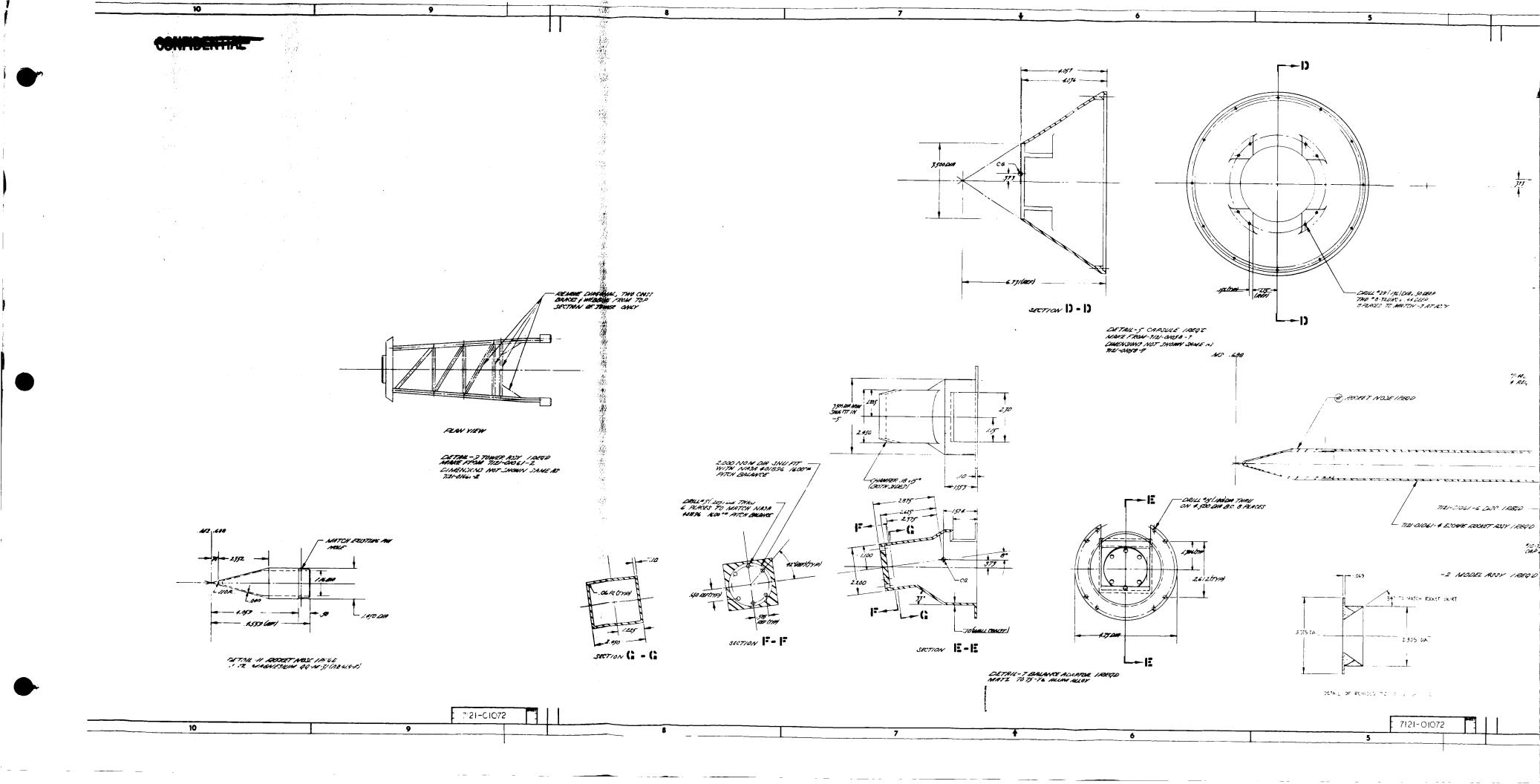
Total length	116.10 in.
Diameter of longitudinal members	3.40 in.
(4 members)	
Diameter of cross braces	2.49 in.
Diameter of diagonal braces	2.49 in.
Distance between attach points	50.18 in.

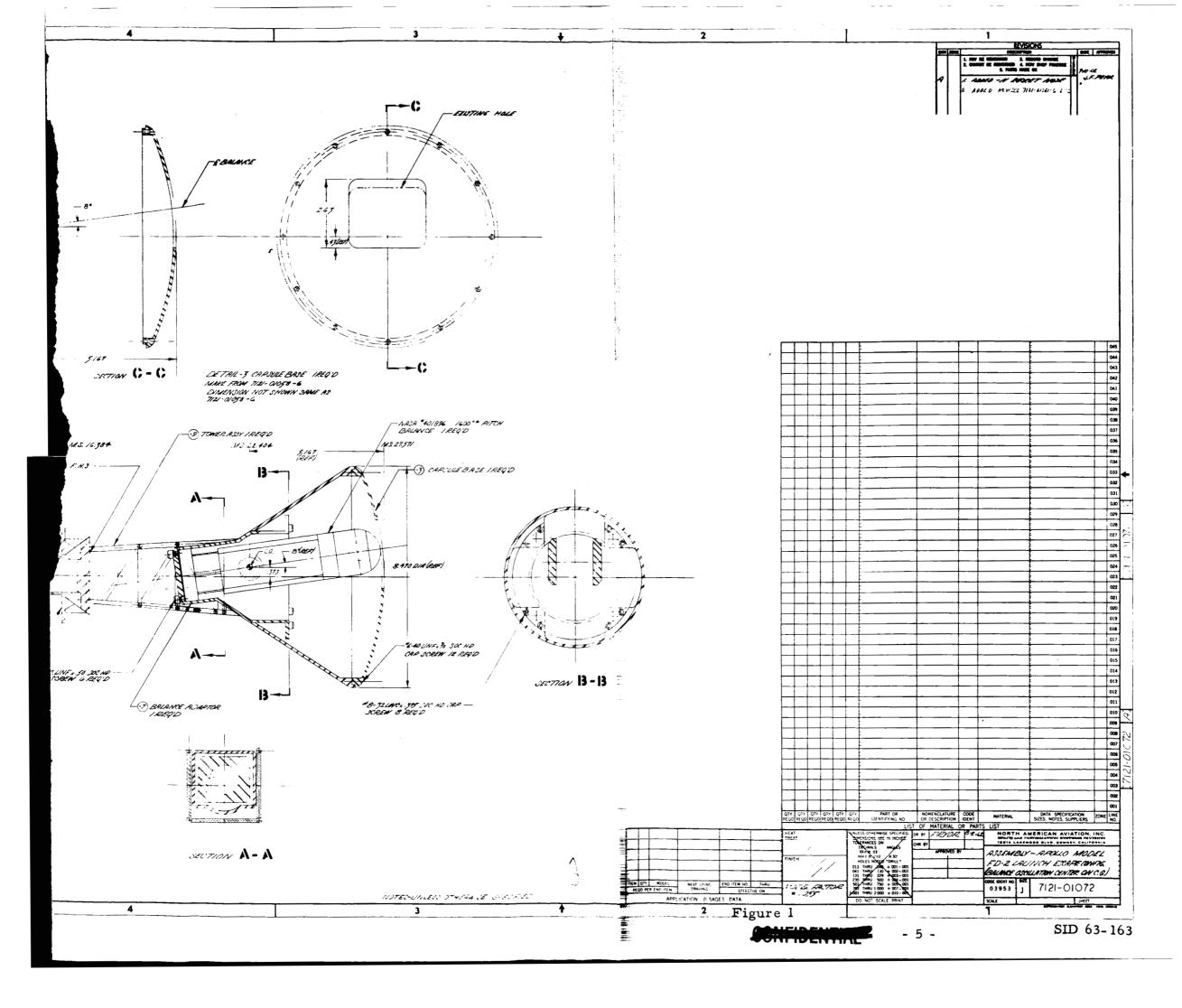
## Command Module, C

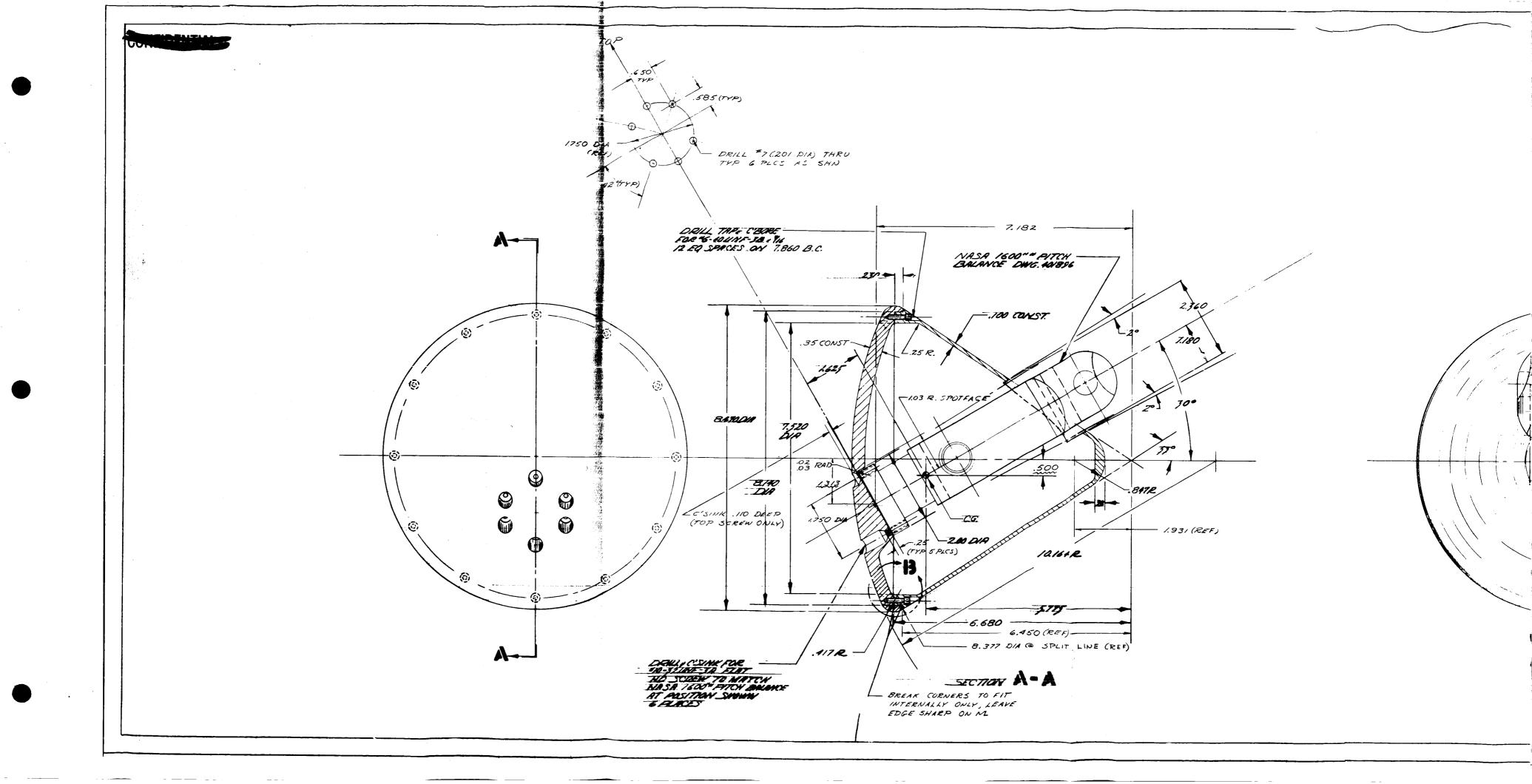
Maximum diameter	154.00 in.
Radius of spherical blunt end	184.80 in.
Corner radius	7.58 in.
Nose cone semiangle	33.00 deg
Nose cone vertex radius	15.40 in.
Frontal area	129.35 ft <sup>2</sup>

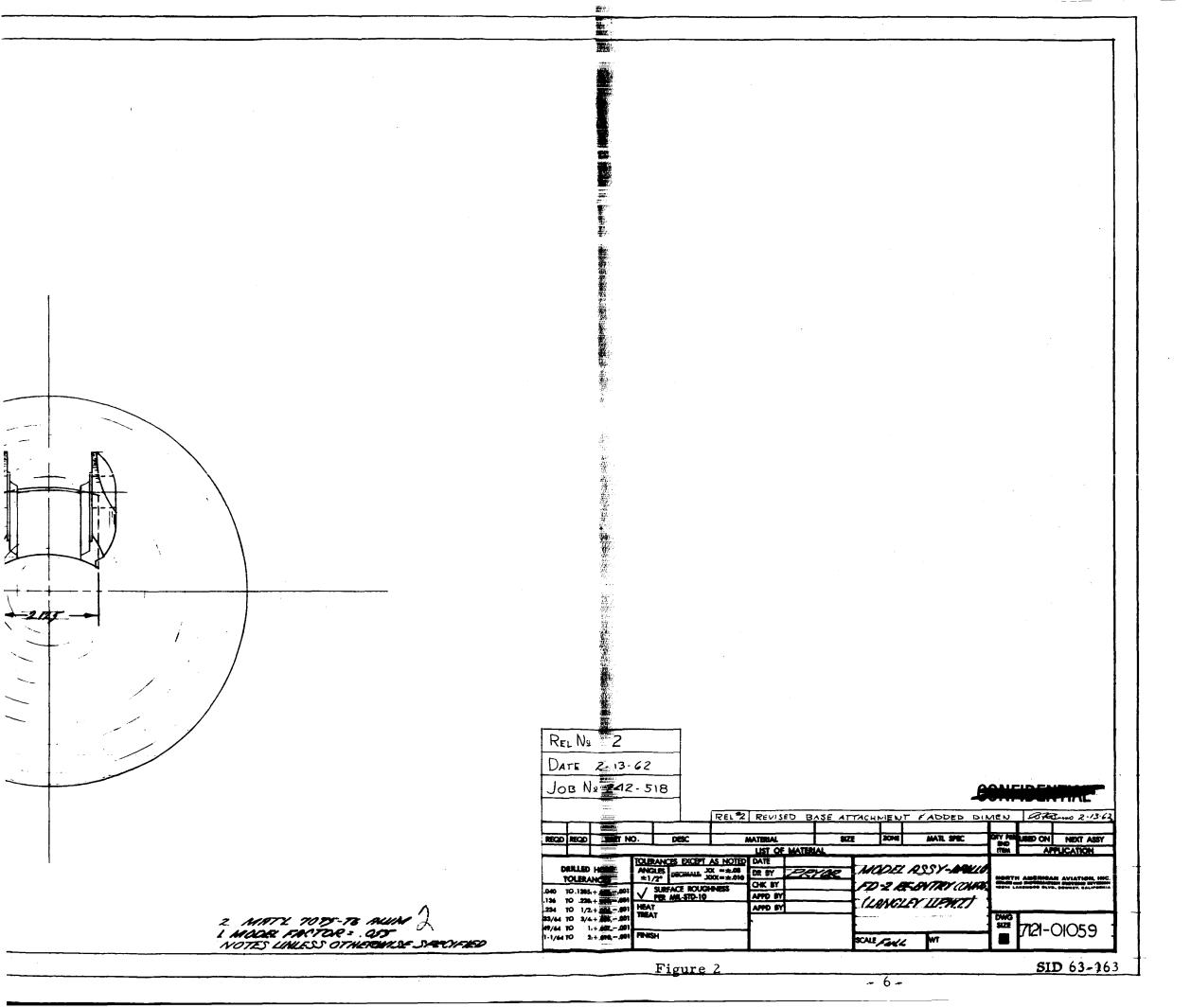
## Command Module, C<sub>19</sub>

Same as C except apex was modified within the confines of the tower legs to allow the oscillation center of the balance to be positioned on the design center of gravity of the full-scale vehicle.



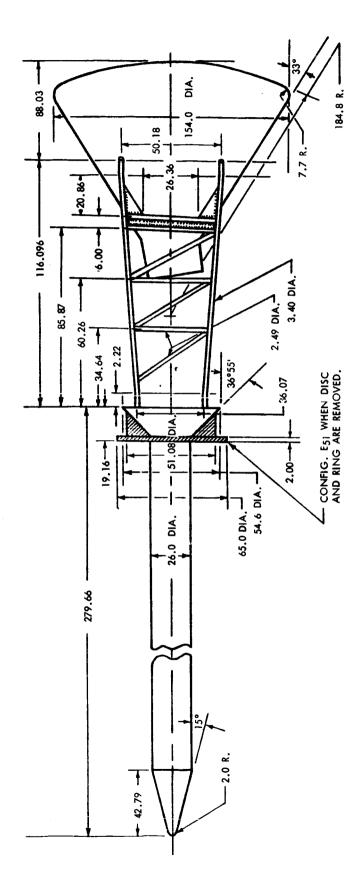










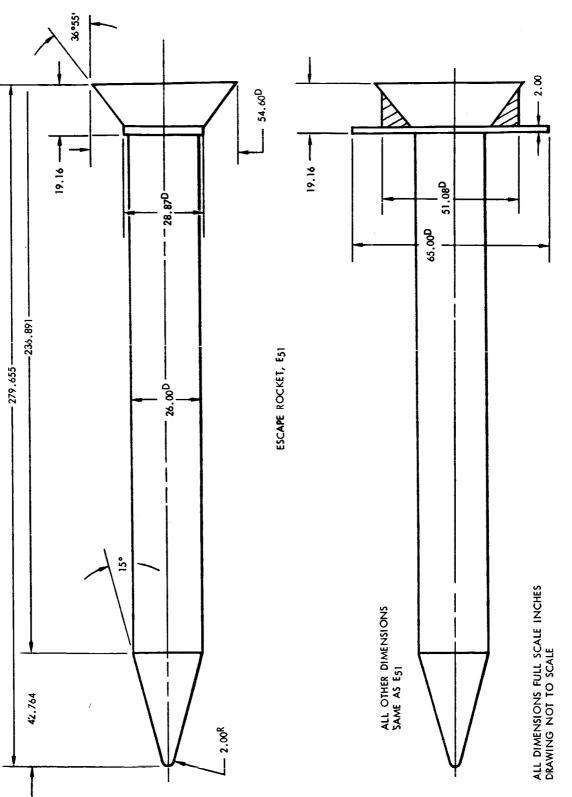


FULL-SCALE DIMENSIONS IN INCHES DRAWING NOT TO SCALE

Figure 3. LEV Configuration E<sub>52</sub>T<sub>21</sub>C<sub>19</sub>



# COMMONTHAL.



ESCAPE ROCKET, E52

Figure 4. Escape Rocket Configurations

# CONTRACTOR

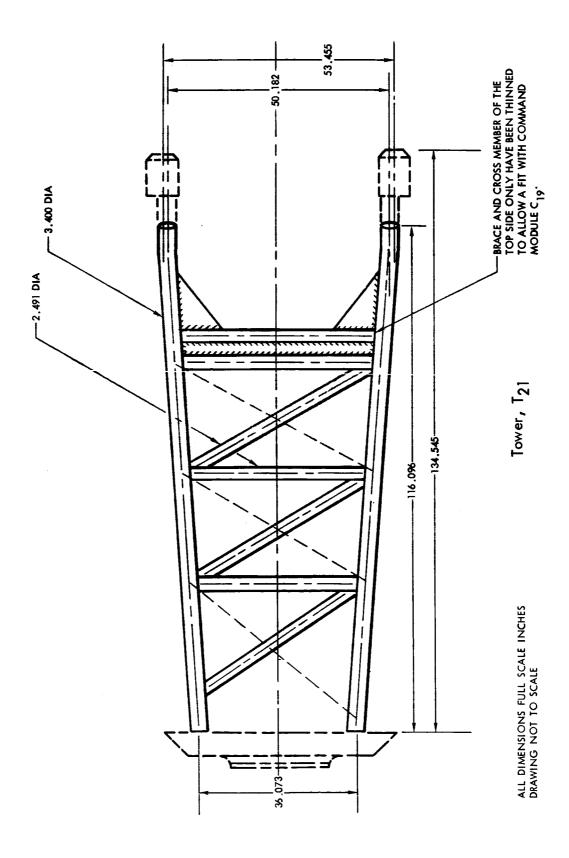
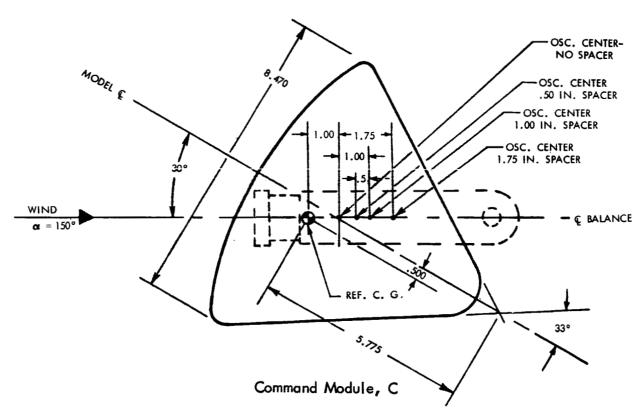


Figure 5. Tower Structure

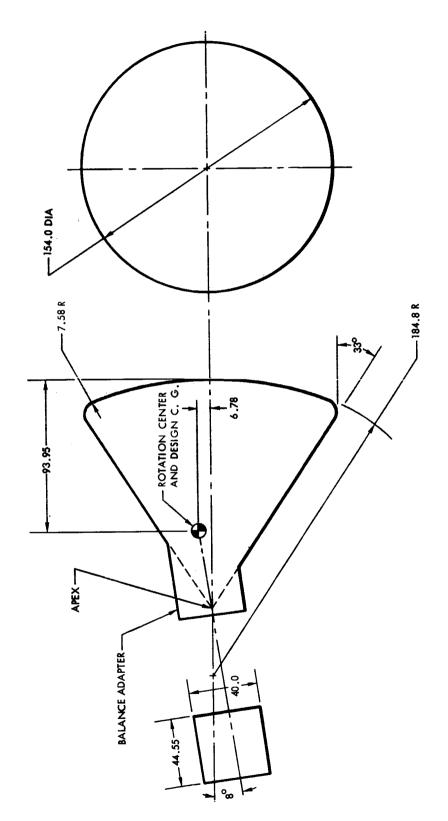


ALL DIMENSIONS MODEL SCALE INCHES DRAWING NOT TO SCALE

Figure 6. Command Module Reentry Configuration
Oscillation Center Location



# Company



ALL DIMENSIONS FULL SCALE INCHES

DRAWING NOT TO SCALE

Command Module, C19

Figure 7. Command Module for LEV Configuration



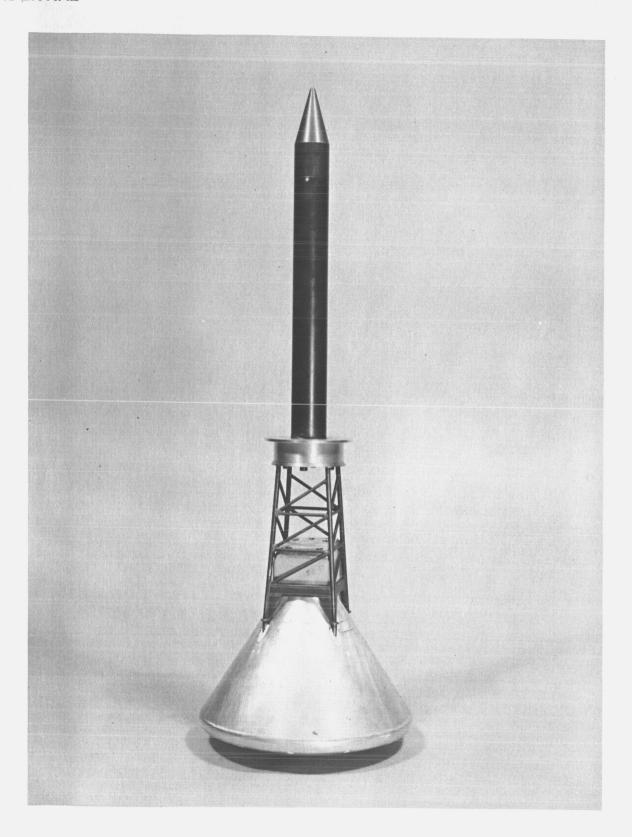


Figure 8. LEV With Flow Separator Disc



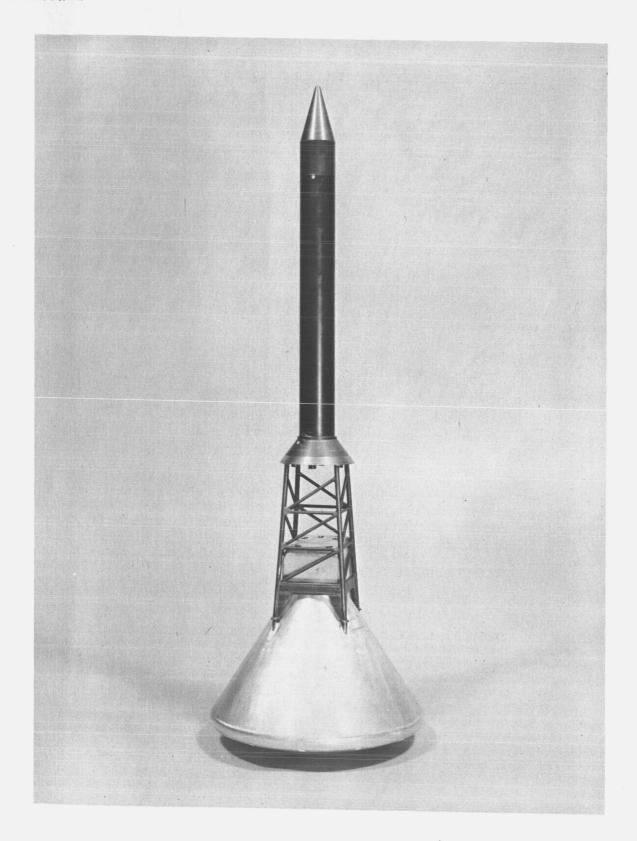


Figure 9. LEV Without Flow Separator Disc





Figure 10. Command Module Reentry Configuration



## IV. TEST PROCEDURE

## TEST NOMENCLATURE

The following nomenclature was used in this investigation.

Maximum cross-sectional area,	ft <sup>2</sup> ,	$\frac{\pi \ell^2}{4}$
	Maximum cross-sectional area,	Maximum cross-sectional area, ft <sup>2</sup> ,

$$\omega$$
 Angular frequency of oscillation, radians/sec

k Reduced frequency parameter, 
$$\frac{\omega \ell}{V}$$

$$C_{m}$$
 Pitching moment coefficient,  $\frac{\text{pitching moment}}{q_{\infty} A \ell}$ 

$$C_{m_q} + C_{m_q^*}$$
 Damping-in-pitch parameter per radian

$$c_{m_{\alpha}}\text{--}\,k^{2}c_{m_{q}}$$
 Oscillatory longitudinal stability parameter per radian





### MODEL INSTALLATION

The FD-2 model was installed on the NASA 1600 inch-pound dynamic balance (Drawing 401896) that was mounted on a straight sting containing the oscillating mechanism. The drive motor, clutch resolvers, and frequency generator were all contained in the downstream end of the sting, which was stiffened to provide a resonant frequency above the maximum oscillating frequency of the model. The oscillating mechanism was designed to provide maximum stiffness of all drive linkages so that the model responded only to the essentially sinusoidal forcing input of the crank and Scotch yoke.

The models were mounted so that the sting centerline and command module axis of symmetry formed a 30-degree angle for the entry configuration to allow testing through angles of attack of 136 to 154 degrees (also 146 to 164 degrees by rolling model 180 degrees) and an 8-degree angle for the launch escape configuration to allow testing through angles of attack of -12 to +6 degrees. The 8-foot Transonic Pressure Tunnel dynamic balance sting support was attached to a tapered vertical strut that was connected to a motor-driven sector. The system was designed to keep the model on the tunnel centerline throughout the angle-of-attack range. In addition, the sting was rigidly braced to the tunnel walls by preloaded stay cables to restrict any sting motion.

### INSTRUMENTATION

The NASA 1600 inch-pound dynamic pitch balance was used to measure the moment and displacement functions as the model was mechanically forced to oscillate in a single degree of freedom.

In operation of the system, calibrated outputs of the moment and displacement strain gages passed through coupled electrical sine-cosine resolvers that rotated at the frequency of oscillation. The resolvers transformed the outputs into orthogonal components from which the resultant applied moment and displacement and the phase angle between them were found. With the known oscillation frequency, the aerodynamic damping and oscillatory stability moments were computed.

All data were computed on a remotely located IBM 7090 computer.

## DATA REDUCTION AND CONSTANTS

All data were reduced and presented in standard NASA coefficient form referred to the body system of axes originating at the oscillation center. The equations used in reducing the data are shown on the following page.





# Comment

C - System damping moment in. -lb/rad/sec

K - System spring constant in, -lb/rad

$$(K - I \omega^2)_{\text{aero}} = (K - I \omega^2)_{\text{run}} - (K - I \omega^2)_{\text{tare}}$$

$$C_{m_q} + C_{m_{\dot{\alpha}}} = -\frac{VC_{aero}}{12 q_{\infty} Al^2}$$

$$C_{m_{\dot{q}}} - k^2 C_{m_{\dot{q}}} = -\frac{(K - I \omega^2)_{aero}}{12 q_{\omega} A l}$$

where

$$k = \frac{\omega L}{V}$$

$$q_{\infty} = 0.7 \text{ p } \text{M}^2$$

$$p = \frac{Stagnation pressure}{(1 + 0.2M^2)^{3.5}}$$

$$V = \frac{(49.0236) \sqrt{T_t} M}{(1 + 0.2M^2)^{1/2}}; T_t = tunnel total temperature, °R$$

Reynolds number = 
$$\frac{2 \ell q_{\infty}}{\mu V}$$
;  $\mu$  = viscosity,  $\frac{lb\text{-sec}}{ft^2}$ 

The following were constants for the test:

$$\ell = 0.7058 \text{ ft}$$

$$A = 0.3912 \text{ ft}^2$$



# COMPLETE

## DATA ACCURACY

The estimated probable errors of the aerodynamic test conditions for this test are as follows:

k, radians  $\pm 0.0001$ 

M  $\pm 0.005$ 

R  $\pm 0.005 \times 10^6$ 

 $\alpha$ , degrees  $\pm 0.1$ 

The ability of the forced oscillation equipment and instrumentation used in these tests to measure accurately the system damping and stability moments is discussed in Reference 5. These accuracies in measuring applied moments, based on repeatability in measuring the wind-off or tare moments of the model and mechanical system when translated to coefficient form using the dimensions of the 0.055-scale Apollo models, give these probable coefficient accuracies:

$$C_{m_q} + C_{m_{\alpha}^{\bullet}} \pm 0.06$$

$$C_{m_{\hat{\mathbf{q}}}} - k^2 C_{m_{\hat{\mathbf{q}}}} \pm 0.03$$





# COMPLETE

### V. REFERENCES

- 1. Data Report for Langley 8-Foot TPT Wind Tunnel Tests (Project 233) of Apollo Model (FD-2). NAA S&ID SID 62-1065 (24 August 1962).
- 2. Data Report for Langley Unitary Plan Wind Tunnel Tests (Project 349) of Apollo Model (FD-2). NAA S&ID SID 62-536 (28 May 1962).
- 3. Data Report for Langley Unitary Plan Wind Tunnel Tests (Project 374) of Apollo Model (FD-2). NAA S&ID SID 62-1074 (24 August 1962).
- 4. Data Report for Tests of a 0.055-Scale Apollo Dynamic Stability Model (FD-2) in the Low Mach Leg of the Langley Unitary Plan Wind Tunnel (Project 398). NAA S&ID SID 63-96 (April 1963).
- 5. Dynamic Longitudinal and Directional Stability Derivatives for a 45-Degree Sweptback-Wing Airplane Model at Transonic Speeds.

  NASA TM X-39 (August 1959).
- 6. Structural Analysis of the 0.055-Scale Apollo Wind Tunnel Models.

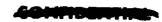
  NAA S&ID SID 62-103 (16 February 1962).

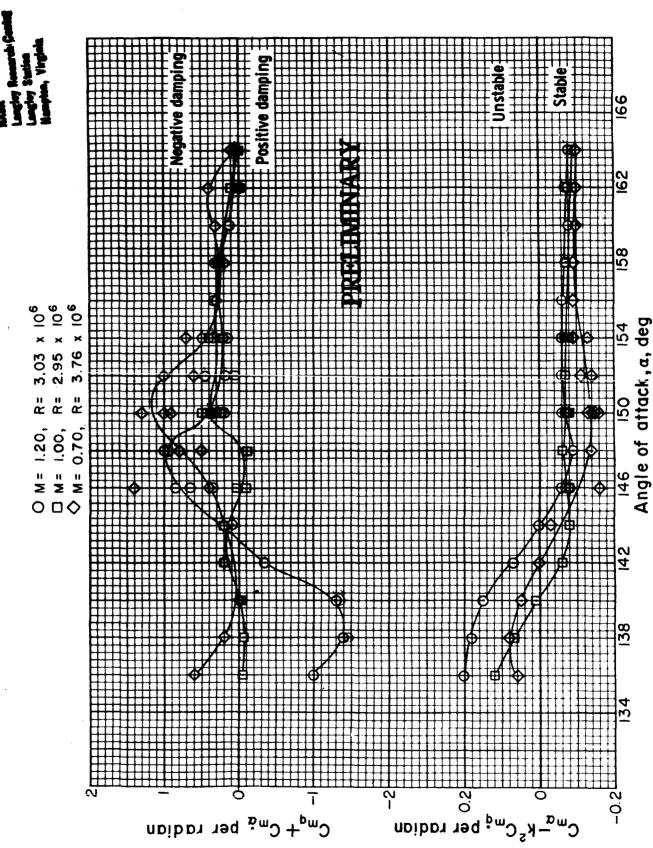


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# APPENDIX A

PLOTTED DATA





A-2

Command Module Entry Configuration, C, with 0.50" Spacer (Runs 1 & 4) Effect of Mach No. Variation on Dynamic Stability Characteristics

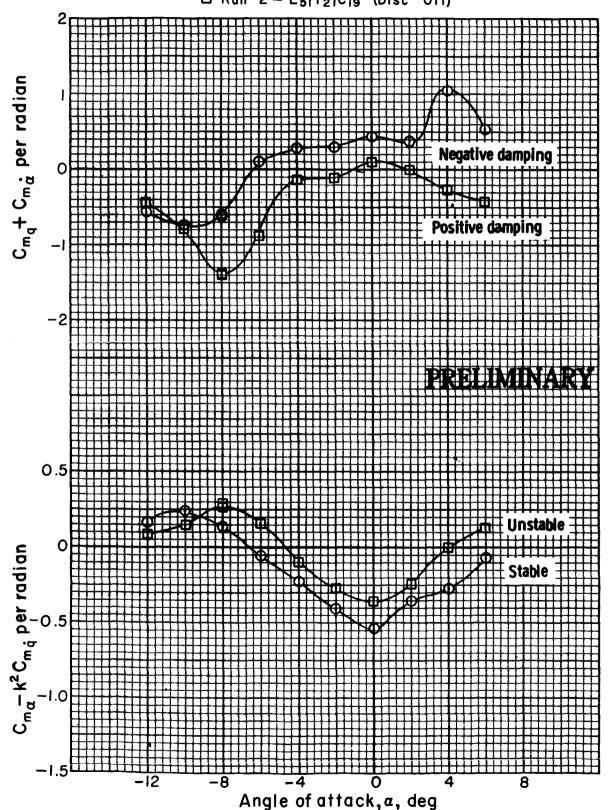


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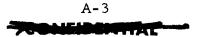


O Run  $3 - E_{52}T_{21}C_{19}$  (Disc On)

Run  $2 - E_{51}T_{21}C_{19}$  (Disc Off)



Effect of Flow Separator Disc on Dynamic Stability Characteristics Launch Escape Configuration, M=0.30 R= 1.78  $\times$  10 $^6$ 



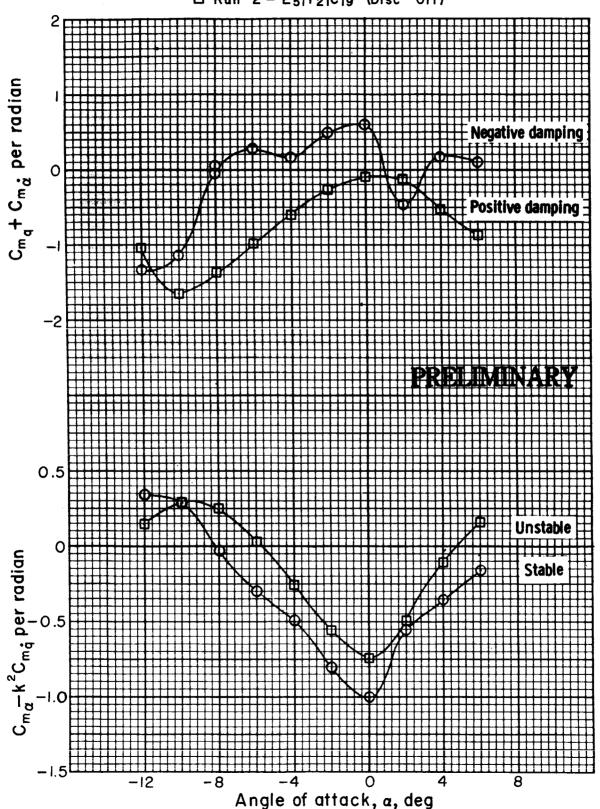


# SOMMENTAL.

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O Run  $3 - E_{52}T_{21}C_{19}$  (Disc On)

Run  $2 - E_{51}T_{21}C_{19}$  (Disc Off)

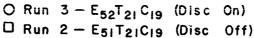


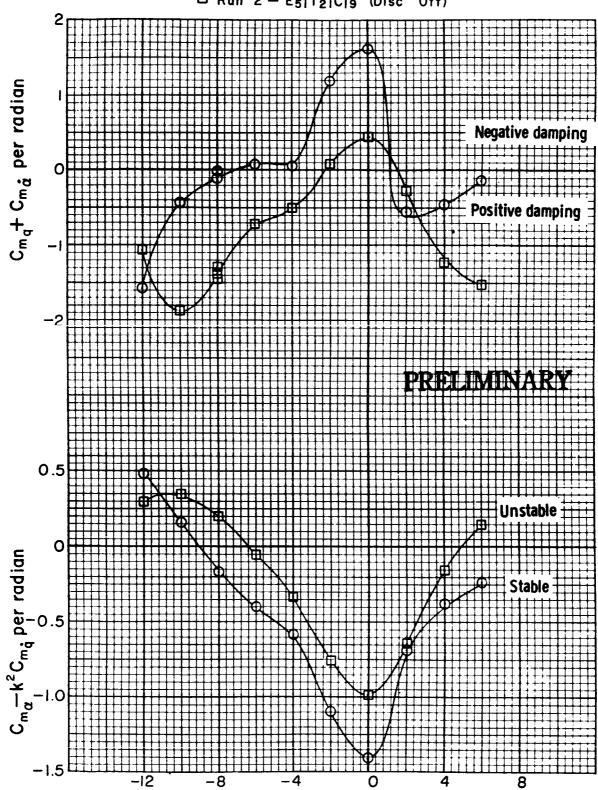
Effect of Flow Separator Disc on Dynamic Stability Characteristics Launch Escape Configuration, M = 0.70 R = 3.02 x  $10^6$ 



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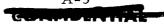
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Langley Research Cente
Langley Station
Hampton, Virginia





Angle of attack,  $\alpha$ , deg

Effect of Flow Separator Disc on Dynamic Stability Characteristics Launch Escape Configuration,  $M = 0.90 R = 2.90 \times 10^6$ 



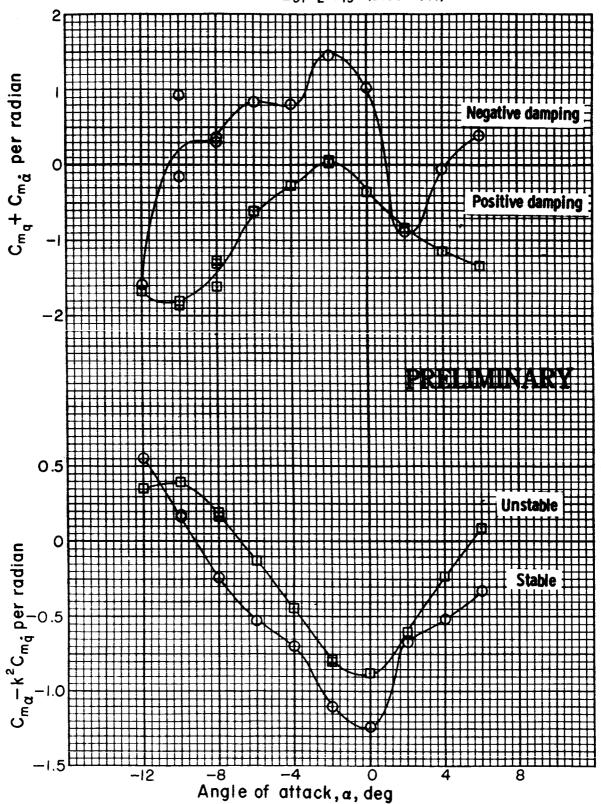


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O Run  $3 - E_{52}T_{21}C_{19}$  (Disc On)

Run  $2 - E_{51}T_2C_{19}$  (Disc Off)



Effect of Flow Separator Disc on Dynamic Stability Characteristics Launch Escape Configuration, M=1.00 R=2.97 x  $10^6$  A=6

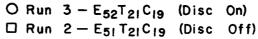


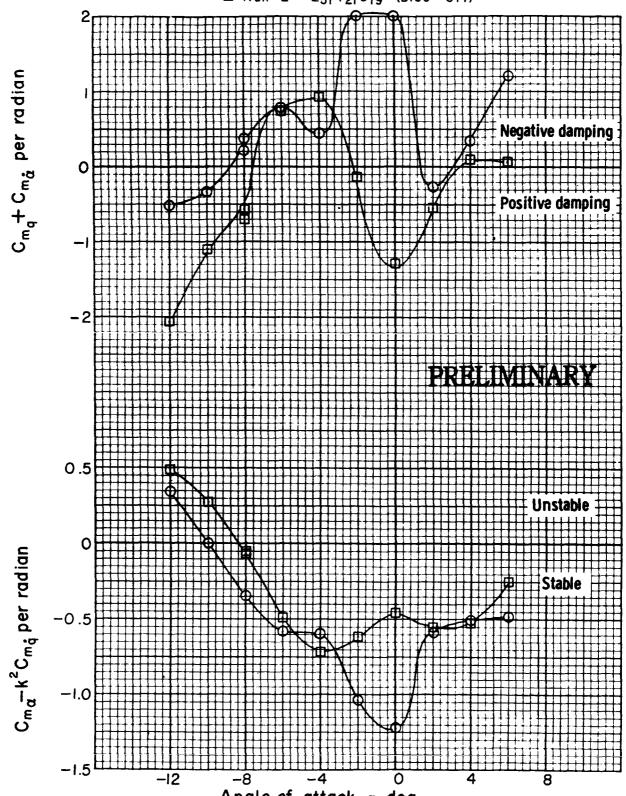
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# COMMENCE

NASA Langley Research Gents Langley Station Magazine, Virginia





Angle of attack,  $\alpha$ , deg

Effect of Flow Separator Disc on Dynamic Stability Characteristics Launch Escape Configuration, M = 1.20 R= 3.05 x  $10^6$ 



CON

# APPENDIX B

TABULATED DATA



# CONTRACTOR

## RUN INDEX

Run No.	Configuration	Mach No.	Angle Range (deg)	R x 10 <sup>-6</sup>	Page ;
1	C - Reentry	0.70	146 to 164	3.76	B-3
	(Command Module	1.00		2.95	B-3
	rolled 180 deg	1.20		3.03	B-4
	0.50-in. spacer)	1.20		3.03	B-4
2	E <sub>51</sub> T <sub>21</sub> C <sub>19</sub>	0.30	-12 to +6	1.75	B-5
	(launch escape	0.70		2.99	B-5
	vehicle, disc	0.90		2.87	B-6
	off)	1.00		2.98	B-6
		1,20		3.05	B-7
.3	E <sub>52</sub> T <sub>21</sub> C <sub>19</sub>	0.30	-12 to +6	1.80	B-7
	(launch escape	0.70		3.05	B-8
	vehicle, disc	0.90		2.93	B-8
	on)	1.00		2.96	B-9
		1,20		3.05	B-9
4	C - Reentry	0.70	136 to 154	3.76	B-10
	(command module	1.00		2.95	B-10
	at 0 deg roll,	1.20		3.03	B-11
	0.50-in. spacer)	1			

## DATA FORMAT

Item or Column Heading	Definition
Config	Configuration No.  90003 - C, 0.50-inch spacer  90010 - E <sub>51</sub> T <sub>21</sub> C <sub>19</sub> 90011 - E <sub>52</sub> T <sub>21</sub> C <sub>19</sub>
Velocity	Free-stream velocity, ft/sec
Q	Free-stream dynamic pressure, lb/ft <sup>2</sup>
R	Reynolds number x 10 <sup>-6</sup> based on a reference length of 0.706 ft
Theta	Phase angle between driving torque and model displacement, deg
Disp	Amplitude of oscillation, radians
Beta	Angle of sideslip, deg
Alpha	Angle of attack, deg
k	Reduced frequency parameter, $\frac{\omega \ell}{V}$
CMQ	Damping-in-pitch parameter per radian, $c_{m_q} + c_{m_{\dot{\alpha}}}$
CMA	Oscillatory longitudinal stability parameter per radian, $C_{m_{\alpha}} - k^2 C_{m_{\alpha}}$



# SHEIDENTIAL

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06 FF. 191 SQ.F1. 10 DEG.F.	1.889- 1.293- 1.293- 1.3914- 1.398- 6.38- 6.11- 6.11- 7.55- 9.30-	706 FT. 391 SG.FT. 110 DEG.F. CMC 1.602- 1.882- 1.882- 1.882- 1.856- 1.557- 1.567-
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8-FT TP 16-23-6	PCINT 8 9 9 11 12 12 13 14 15 17 18 17 18	8-FT T 10-23- 10-23- 22- 22- 22- 22- 23- 23- 23- 23- 23-
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	0082- 271- 1700- 1	CMA 124 159 159 222- 407- 531-	36 27 06
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6 FT 1 SC.FT. 0 DEG.F.	CMC 2655- 1.559- 1.559- 1.50- 1.50- 1.50-	6 FT. 1 SG.FT. CMC. 384- 1.904- 1.206- 206- 217- 1.571 .815- .815- .832-
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TENCE LENG RENCE AREA TEMPERATE	ALPHA 150.00 152.00 154.00 146.00 144.01 140.01 138.00	RENCE LEN RENCE LEN L TEMPERA 150.00 152.00 152.00 152.00 146.00 146.00 145.01 145.01 135.99
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